

CSCI567 Machine Learning (Spring 2025)

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Administration

HW1 was due yesterday. Remember: only one late day allowed

HW2 will be released next week.

Outline

- 1 Review of Last Lecture
- 2 Multiclass Classification
- 3 Neural Nets

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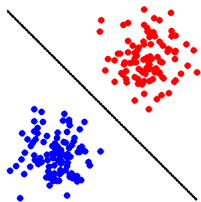
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Linear classifiers

Linear models for **binary** classification:

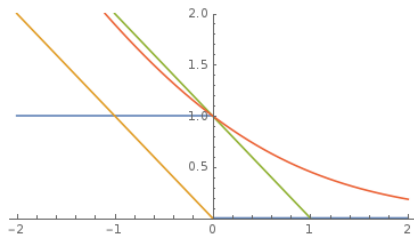
Step 1. Model is the set of **separating hyperplanes**

$$\mathcal{F} = \{f(\mathbf{x}) = \text{sgn}(\mathbf{w}^T \mathbf{x}) \mid \mathbf{w} \in \mathbb{R}^D\}$$



Linear classifiers

Step 2. Pick the **surrogate loss**



- **perceptron loss** $l_{\text{perceptron}}(z) = \max\{0, -z\}$ (used in Perceptron)
- **hinge loss** $l_{\text{hinge}}(z) = \max\{0, 1 - z\}$ (used in SVM and many others)
- **logistic loss** $l_{\text{logistic}}(z) = \log(1 + \exp(-z))$ (used in logistic regression)

Linear classifiers

Step 3. Find empirical risk minimizer (ERM):

$$\mathbf{w}^* = \operatorname{argmin}_{\mathbf{w} \in \mathbb{R}^D} F(\mathbf{w}) = \operatorname{argmin}_{\mathbf{w} \in \mathbb{R}^D} \frac{1}{N} \sum_{n=1}^N \ell(y_n \mathbf{w}^T \mathbf{x}_n)$$

using

- **GD:** $\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla F(\mathbf{w})$
- **SGD:** $\mathbf{w} \leftarrow \mathbf{w} - \eta \tilde{\nabla} F(\mathbf{w})$ $(\mathbb{E}[\tilde{\nabla} F(\mathbf{w})] = \nabla F(\mathbf{w}))$
- **Newton:** $\mathbf{w} \leftarrow \mathbf{w} - (\nabla^2 F(\mathbf{w}))^{-1} \nabla F(\mathbf{w})$

Convergence guarantees of GD/SGD

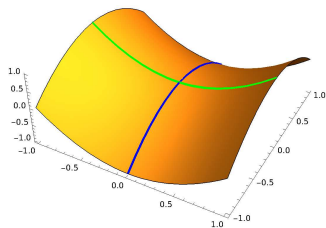
- GD/SGD converges to a stationary point

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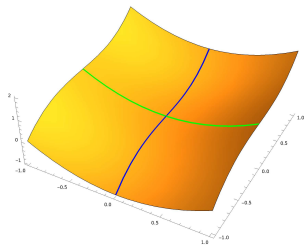
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Convergence guarantees of GD/SGD

- GD/SGD converges to a stationary point
- for convex objectives, this is all we need
- for nonconvex objectives, can get stuck at local minimizers or “bad” saddle points (random initialization escapes “good” saddle points)



“good” saddle points



“bad” saddle points

Perceptron and logistic regression

Initialize $w = \mathbf{0}$ or randomly.

Repeat:

- pick a data point x_n uniformly at random (**common trick for SGD**)

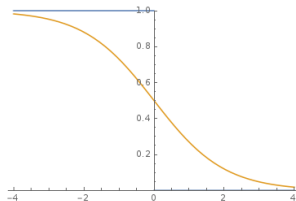
Perceptron and logistic regression

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Repeat:

- pick a data point \mathbf{x}_n uniformly at random (**common trick for SGD**)
- update parameter:

$$\mathbf{w} \leftarrow \mathbf{w} + \begin{cases} \mathbb{I}[y_n \mathbf{w}^T \mathbf{x}_n \leq 0] y_n \mathbf{x}_n & \text{(Perceptron)} \\ \eta \sigma(-y_n \mathbf{w}^T \mathbf{x}_n) y_n \mathbf{x}_n & \text{(logistic regression)} \end{cases}$$



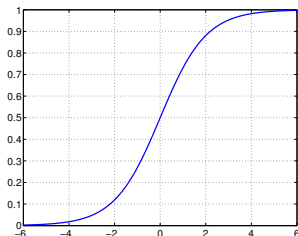
A Probabilistic view of logistic regression

Minimizing logistic loss = MLE for the sigmoid model

$$\mathbf{w}^* = \operatorname{argmin}_{\mathbf{w}} \sum_{n=1}^N \ell_{\text{logistic}}(y_n \mathbf{w}^T \mathbf{x}_n) = \operatorname{argmax}_{\mathbf{w}} \prod_{n=1}^N \mathbb{P}(y_n \mid \mathbf{x}_n; \mathbf{w})$$

where

$$\mathbb{P}(y \mid \mathbf{x}; \mathbf{w}) = \sigma(y \mathbf{w}^T \mathbf{x}) = \frac{1}{1 + e^{-y \mathbf{w}^T \mathbf{x}}}$$



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- 2 Multiclass Classification
 - Multinomial logistic regression
 - Reduction to binary classification
- 3 Neural Nets

Classification

Recall the setup:

- input (feature vector): $\mathbf{x} \in \mathbb{R}^D$
- output (label): $y \in [C] = \{1, 2, \dots, C\}$
- goal: learn a mapping $f : \mathbb{R}^D \rightarrow [C]$

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Examples:

- recognizing digits ($C = 10$) or letters ($C = 26$ or 52)
- predicting weather: sunny, cloudy, rainy, etc
- predicting image category: ImageNet dataset ($C \approx 20K$)

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Nearest Neighbor Classifier naturally works for arbitrary C .

Linear models: from binary to multiclass

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$$f(\mathbf{x}) = \begin{cases} 1 & \text{if } \mathbf{w}^T \mathbf{x} \geq 0 \\ 2 & \text{if } \mathbf{w}^T \mathbf{x} < 0 \end{cases}$$

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for any $\mathbf{w}_1, \mathbf{w}_2$ s.t. $\mathbf{w} = \mathbf{w}_1 - \mathbf{w}_2$

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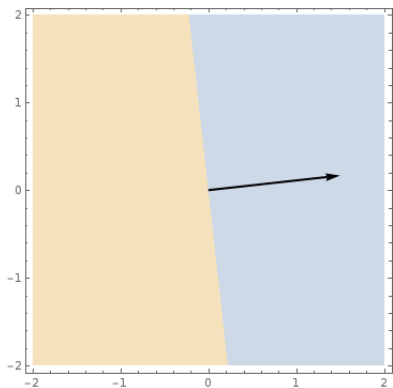
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for any $\mathbf{w}_1, \mathbf{w}_2$ s.t. $\mathbf{w} = \mathbf{w}_1 - \mathbf{w}_2$

Think of $\mathbf{w}_k^T \mathbf{x}$ as **a score for class k** .

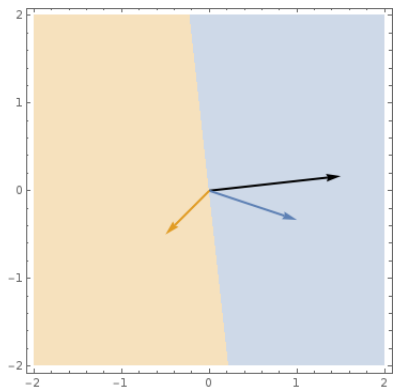
Linear models: from binary to multiclass



$$\mathbf{w} = \left(\frac{3}{2}, \frac{1}{6}\right)$$

- Blue class:
 $\{\mathbf{x} : \mathbf{w}^T \mathbf{x} \geq 0\}$
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 $\{\mathbf{x} : \mathbf{w}^T \mathbf{x} < 0\}$

Linear models: from binary to multiclass



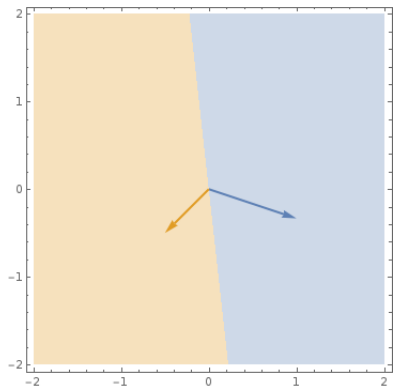
$$\mathbf{w} = \left(\frac{3}{2}, \frac{1}{6}\right) = \mathbf{w}_1 - \mathbf{w}_2$$

$$\mathbf{w}_1 = \left(1, -\frac{1}{3}\right)$$

$$\mathbf{w}_2 = \left(-\frac{1}{2}, -\frac{1}{2}\right)$$

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 $\{\mathbf{x} : 1 = \operatorname{argmax}_k \mathbf{w}_k^T \mathbf{x}\}$
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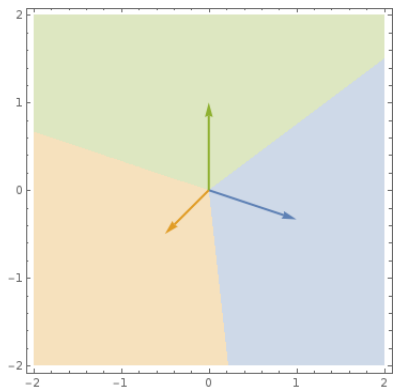


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Linear models: from binary to multiclass



$$\mathbf{w}_1 = (1, -\frac{1}{3})$$

$$\mathbf{w}_2 = (-\frac{1}{2}, -\frac{1}{2})$$

$$\mathbf{w}_3 = (0, 1)$$

- Blue class:
 $\{\mathbf{x} : 1 = \operatorname{argmax}_k \mathbf{w}_k^T \mathbf{x}\}$
- Orange class:
 $\{\mathbf{x} : 2 = \operatorname{argmax}_k \mathbf{w}_k^T \mathbf{x}\}$
- Green class:
 $\{\mathbf{x} : 3 = \operatorname{argmax}_k \mathbf{w}_k^T \mathbf{x}\}$

Linear models for multiclass classification

$$\mathcal{F} = \left\{ f(\mathbf{x}) = \operatorname{argmax}_{k \in [C]} \mathbf{w}_k^T \mathbf{x} \mid \mathbf{w}_1, \dots, \mathbf{w}_C \in \mathbb{R}^D \right\}$$

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Step 2: *How do we generalize perceptron/hinge/logistic loss?*

This lecture: focus on the more popular **logistic loss**

Multinomial logistic regression: a probabilistic view

Observe: for binary logistic regression, with $\mathbf{w} = \mathbf{w}_1 - \mathbf{w}_2$:

$$\mathbb{P}(y = 1 \mid \mathbf{x}; \mathbf{w}) = \sigma(\mathbf{w}^T \mathbf{x}) = \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}} = \frac{e^{\mathbf{w}_1^T \mathbf{x}}}{e^{\mathbf{w}_1^T \mathbf{x}} + e^{\mathbf{w}_2^T \mathbf{x}}} \propto e^{\mathbf{w}_1^T \mathbf{x}}$$

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Naturally, for multiclass:

$$\mathbb{P}(y = k \mid \mathbf{x}; \mathbf{W}) = \frac{e^{\mathbf{w}_k^T \mathbf{x}}}{\sum_{k' \in [C]} e^{\mathbf{w}_{k'}^T \mathbf{x}}} \propto e^{\mathbf{w}_k^T \mathbf{x}}$$

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This is called the *softmax function*.

Applying MLE again

Maximize probability of seeing labels y_1, \dots, y_N given $\mathbf{x}_1, \dots, \mathbf{x}_N$

$$P(\mathbf{W}) = \prod_{n=1}^N \mathbb{P}(y_n \mid \mathbf{x}_n; \mathbf{W}) = \prod_{n=1}^N \frac{e^{\mathbf{w}_{y_n}^T \mathbf{x}_n}}{\sum_{k \in [C]} e^{\mathbf{w}_k^T \mathbf{x}_n}}$$

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By taking **negative log**, this is equivalent to minimizing

$$F(\mathbf{W}) = \sum_{n=1}^N \ln \left(\frac{\sum_{k \in [C]} e^{\mathbf{w}_k^T \mathbf{x}_n}}{e^{\mathbf{w}_{y_n}^T \mathbf{x}_n}} \right)$$

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When $C = 2$, this is the same as binary logistic loss.

Step 3: Optimization

Apply **SGD**: what is the gradient of

$$F_n(\mathbf{W}) = \ln \left(1 + \sum_{k' \neq y_n} e^{(\mathbf{w}_{k'} - \mathbf{w}_{y_n})^T \mathbf{x}_n} \right) ?$$

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It's a $C \times D$ matrix. Let's focus on the k -th row:

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SGD for multinomial logistic regression

Initialize $\mathbf{W} = \mathbf{0}$ (or randomly). Repeat:

- 1 pick $n \in [N]$ uniformly at random
- 2 update the parameters

$$\mathbf{W} \leftarrow \mathbf{W} - \eta \begin{pmatrix} \mathbb{P}(y = 1 \mid \mathbf{x}_n; \mathbf{W}) \\ \vdots \\ \mathbb{P}(y = y_n \mid \mathbf{x}_n; \mathbf{W}) - 1 \\ \vdots \\ \mathbb{P}(y = C \mid \mathbf{x}_n; \mathbf{W}) \end{pmatrix} \mathbf{x}_n^T$$

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Think about why the algorithm makes sense intuitively.

A note on prediction

Having learned \mathbf{W} , we can either

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Having learned \mathbf{W} , we can either

- make a *deterministic* prediction $\operatorname{argmax}_{k \in [C]} \mathbf{w}_k^\top \mathbf{x}$
- make a *randomized* prediction according to $\mathbb{P}(k \mid \mathbf{x}; \mathbf{W}) \propto e^{\mathbf{w}_k^\top \mathbf{x}}$

Generalization of cross-entropy loss

Given a general model class:

$$\mathcal{F} = \left\{ f(\mathbf{x}) = \operatorname{argmax}_{k \in [C]} s_k(\mathbf{x}) \right\}$$

where s_k is the **“scoring” function** for class k .

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where s_k is the **“scoring” function** for class k .

The cross-entropy loss of f for a training sample (\mathbf{x}, y) is

$$-\ln \left(\frac{e^{s_y(\mathbf{x})}}{\sum_{k \in [C]} e^{s_k(\mathbf{x})}} \right) = \ln \left(1 + \sum_{k \neq y} e^{s_k(\mathbf{x}) - s_y(\mathbf{x})} \right)$$

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Given a binary classification algorithm (*any one*, not just linear methods), can we turn it to a multiclass algorithm, *in a black-box manner*?

Yes, there are in fact many ways to do it.

- **one-versus-all** (one-versus-rest, one-against-all, etc.)
- **one-versus-one** (all-versus-all, etc.)
- **Error-Correcting Output Codes** (ECOC)
- **tree-based reduction**

One-versus-all (OvA)

(picture credit: [link](#))

Idea: train C binary classifiers to learn “**is class k or not?**” for each k .

One-versus-all (OvA)

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Idea: train C binary classifiers to learn “**is class k or not?**” for each k .

Training: for each class $k \in [C]$,

- relabel examples with class k as $+1$, and all others as -1
- train a binary classifier h_k using this new dataset

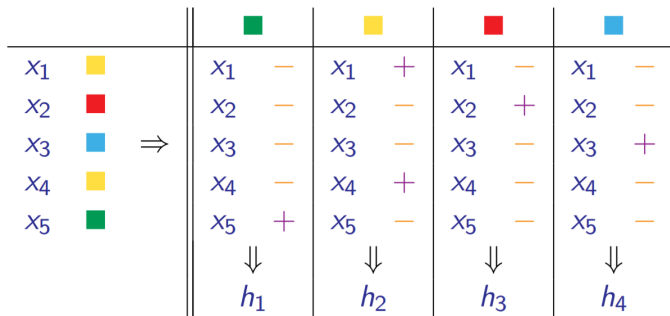
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Prediction: for a new example \mathbf{x}

- ask each h_k : **does this belong to class k ?** (i.e. $h_k(\mathbf{x})$)

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- randomly pick among all k 's s.t. $h_k(\mathbf{x}) = +1$.

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Issue: will (probably) make a mistake *as long as one of h_k errs*.

One-versus-one (OvO)

(picture credit: [link](#))

Idea: train $\binom{C}{2}$ binary classifiers to learn “**is class k or k' ?**”.

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Training: for each pair (k, k') ,

- relabel examples with class k as $+1$ and examples with class k' as -1
- *discard all other examples*
- train a binary classifier $h_{(k,k')}$ using this new dataset

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	■ vs. ■	■ vs. ■	■ vs. ■	■ vs. ■	■ vs. ■	■ vs. ■
x_1 ■	x_1 —			x_1 —		x_1 —
x_2 ■		x_2 —	x_2 +			x_2 +
x_3 ■ \Rightarrow			x_3 —	x_3 +	x_3 —	
x_4 ■	x_4 —			x_4 —		x_4 —
x_5 ■	x_5 +	x_5 +			x_5 +	
	\Downarrow	\Downarrow	\Downarrow	\Downarrow	\Downarrow	\Downarrow
	$h_{(1,2)}$	$h_{(1,3)}$	$h_{(3,4)}$	$h_{(4,2)}$	$h_{(1,4)}$	$h_{(3,2)}$

One-versus-one (OvO)

Prediction: for a new example \mathbf{x}

- ask each classifier $h_{(k,k')}$ to **vote for either class k or k'**

One-versus-one (OvO)

Prediction: for a new example x

- ask each classifier $h_{(k,k')}$ to **vote for either class k or k'**
- predict the class with the most votes (break tie in some way)

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Prediction: for a new example x

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More robust than one-versus-all, but *slower* in prediction.

Error-correcting output codes (ECOC)

(picture credit: [link](#))

Idea: based on a code $M \in \{-1, +1\}^{C \times L}$, train L binary classifiers to learn “**is bit b on or off**”.

M	1	2	3	4	5
■	+	-	+	-	+
■	-	-	+	+	+
■	+	+	-	-	-
■	+	+	+	+	-

Error-correcting output codes (ECOC)

(picture credit: [link](#))

Idea: based on a code $M \in \{-1, +1\}^{C \times L}$, train L binary classifiers to learn “is bit b on or off”.

Training: for each bit $b \in [L]$

- relabel example x_n as $M_{y_n, b}$
- train a binary classifier h_b using this new dataset.

M	1	2	3	4	5
■	+	-	+	-	+
■	-	-	+	+	+
■	+	+	-	-	-
■	+	+	+	+	-

	1	2	3	4	5
x_1 ■	x_1 -	x_1 -	x_1 +	x_1 +	x_1 +
x_2 ■	x_2 +	x_2 +	x_2 -	x_2 -	x_2 -
x_3 ■	x_3 +	x_3 +	x_3 +	x_3 +	x_3 -
x_4 ■	x_4 -	x_4 -	x_4 +	x_4 +	x_4 +
x_5 ■	x_5 +	x_5 -	x_5 +	x_5 -	x_5 +
	⇓	⇓	⇓	⇓	⇓
	h_1	h_2	h_3	h_4	h_5

Error-correcting output codes (ECOC)

Prediction: for a new example \mathbf{x}

- compute the **predicted code** $\mathbf{c} = (h_1(\mathbf{x}), \dots, h_L(\mathbf{x}))^T$

Error-correcting output codes (ECOC)

Prediction: for a new example \mathbf{x}

- compute the **predicted code** $\mathbf{c} = (h_1(\mathbf{x}), \dots, h_L(\mathbf{x}))^T$
- predict the class with the **most similar code**: $k = \operatorname{argmax}_k (\mathbf{M}\mathbf{c})_k$

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How to design the code \mathbf{M} ?

- the more *dissimilar* the codes, the more robust
 - if any two codes are d bits away, then prediction can tolerate about $d/2$ errors
- *random code* is often a good choice














Tree based method

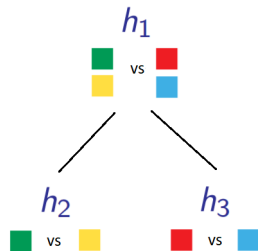
Idea: train $\approx C$ binary classifiers to learn “**belongs to which half?**”.

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Training: see pictures














		 vs   vs 	 vs 	 vs 
x_1		x_1 +	x_1 -	
x_2		x_2 -		x_2 +
x_3		x_3 -		x_3 -
x_4		x_4 +	x_4 -	
x_5		x_5 +	x_5 +	
		↓ h_1	↓ h_2	↓ h_3

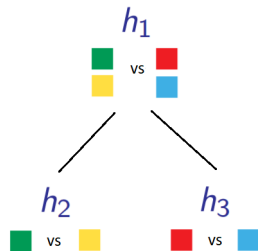


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Training: see pictures

		 vs   vs 	 vs 	 vs 
x_1		x_1 +	x_1 -	
x_2		x_2 -		x_2 +
x_3		x_3 -		x_3 -
x_4		x_4 +	x_4 -	
x_5		x_5 +	x_5 +	
		↓	↓	↓
		h_1	h_2	h_3
















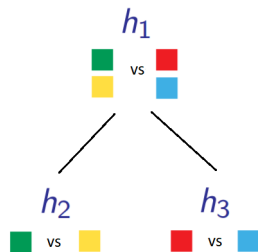
Prediction is also natural,

Tree based method

Idea: train $\approx C$ binary classifiers to learn “**belongs to which half?**”.

Training: see pictures

		 vs   vs 	 vs 	 vs 
x_1		x_1 +	x_1 -	
x_2		x_2 -		x_2 +
x_3		x_3 -		x_3 -
x_4		x_4 +	x_4 -	
x_5		x_5 +	x_5 +	
		↓	↓	↓
		h_1	h_2	h_3



Prediction is also natural, *but is very fast!* (think ImageNet where $C \approx 20K$)

Comparisons

Reduction	training time	prediction time	remark

training time: how many training points are created

prediction time: how many binary predictions are made

Comparisons

Reduction	training time	prediction time	remark
OvA			

training time: how many

training points are created

prediction time: how many

binary predictions are made

	■	■	■	■
x_1 ■	x_1 -	x_1 +	x_1 -	x_1 -
x_2 ■	x_2 -	x_2 -	x_2 +	x_2 -
x_3 ■	x_3 -	x_3 -	x_3 -	x_3 +
x_4 ■	x_4 -	x_4 +	x_4 -	x_4 -
x_5 ■	x_5 +	x_5 -	x_5 -	x_5 -
	↓	↓	↓	↓
	h_1	h_2	h_3	h_4

Comparisons

Reduction	training time	prediction time	remark
OvA	CN		

training time: how many

training points are created

prediction time: how many

binary predictions are made

	■	■	■	■
x_1	■	x_1 -	x_1 +	x_1 -
x_2	■	x_2 -	x_2 -	x_2 +
x_3	■	x_3 -	x_3 -	x_3 +
x_4	■	x_4 -	x_4 +	x_4 -
x_5	■	x_5 +	x_5 -	x_5 -
		↓	↓	↓
		h_1	h_2	h_3

Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	

training time: how many

training points are created

prediction time: how many

binary predictions are made

	■	■	■	■
x_1	■	x_1 -	x_1 +	x_1 -
x_2	■	x_2 -	x_2 -	x_2 +
x_3	■	x_3 -	x_3 -	x_3 +
x_4	■	x_4 -	x_4 +	x_4 -
x_5	■	x_5 +	x_5 -	x_5 -
		↓	↓	↓
		h_1	h_2	h_3

Comparisons

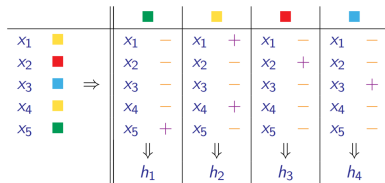
Reduction	training time	prediction time	remark
OvA	CN	C	not robust

training time: how many

training points are created

prediction time: how many

binary predictions are made



Comparisons

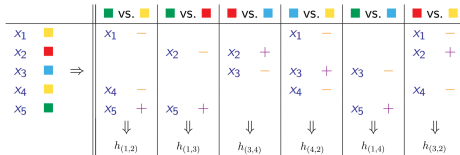
Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO			

training time: how many

training points are created

prediction time: how many

binary predictions are made



Comparisons

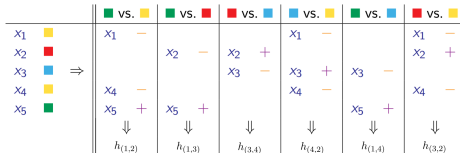
Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$		

training time: how many

training points are created

prediction time: how many

binary predictions are made



Comparisons

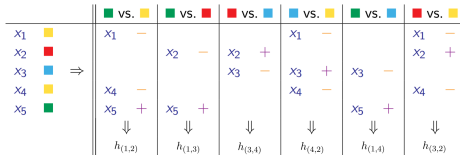
Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	

training time: how many

training points are created

prediction time: how many

binary predictions are made



Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error

training time: how many

training points are created

prediction time: how many

binary predictions are made

	■ vs. ■	■ vs. ■	■ vs. ■	■ vs. ■	■ vs. ■	■ vs. ■
x ₁ ■	x ₁ -			x ₁ -		x ₁ -
x ₂ ■		x ₂ -	x ₂ +			x ₂ +
x ₃ ■			x ₃ -	x ₃ +	x ₃ -	
x ₄ ■	x ₄ -			x ₄ -		x ₄ -
x ₅ ■	x ₅ +	x ₅ +			x ₅ +	
	⇓	⇓	⇓	⇓	⇓	⇓
	h _(1,2)	h _(1,3)	h _(3,4)	h _(4,2)	h _(1,4)	h _(3,2)

Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC			

training time: how many training points are created

prediction time: how many binary predictions are made

		1	2	3	4	5
x_1	■	$x_1 -$	$x_1 -$	$x_1 +$	$x_1 +$	$x_1 +$
x_2	■	$x_2 +$	$x_2 +$	$x_2 -$	$x_2 -$	$x_2 -$
x_3	■	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 -$
x_4	■	$x_4 -$	$x_4 -$	$x_4 +$	$x_4 +$	$x_4 +$
x_5	■	$x_5 +$	$x_5 -$	$x_5 +$	$x_5 -$	$x_5 +$
		↓	↓	↓	↓	↓
		h_1	h_2	h_3	h_4	h_5

Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC	LN		

training time: how many training points are created

prediction time: how many binary predictions are made

		1	2	3	4	5
x_1	■	$x_1 -$	$x_1 -$	$x_1 +$	$x_1 +$	$x_1 +$
x_2	■	$x_2 +$	$x_2 +$	$x_2 -$	$x_2 -$	$x_2 -$
x_3	■	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 -$
x_4	■	$x_4 -$	$x_4 -$	$x_4 +$	$x_4 +$	$x_4 +$
x_5	■	$x_5 +$	$x_5 -$	$x_5 +$	$x_5 -$	$x_5 +$
		↓	↓	↓	↓	↓
		h_1	h_2	h_3	h_4	h_5

Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC	LN	L	

training time: how many training points are created

prediction time: how many binary predictions are made

		1	2	3	4	5
x_1	■	$x_1 -$	$x_1 -$	$x_1 +$	$x_1 +$	$x_1 +$
x_2	■	$x_2 +$	$x_2 +$	$x_2 -$	$x_2 -$	$x_2 -$
x_3	■	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 -$
x_4	■	$x_4 -$	$x_4 -$	$x_4 +$	$x_4 +$	$x_4 +$
x_5	■	$x_5 +$	$x_5 -$	$x_5 +$	$x_5 -$	$x_5 +$
		↓	↓	↓	↓	↓
		h_1	h_2	h_3	h_4	h_5

Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC	LN	L	need diversity when designing code

training time: how many training points are created

prediction time: how many binary predictions are made

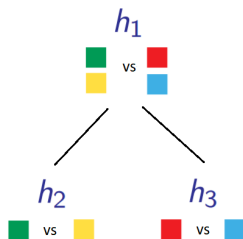
		1	2	3	4	5
x_1	■	$x_1 -$	$x_1 -$	$x_1 +$	$x_1 +$	$x_1 +$
x_2	■	$x_2 +$	$x_2 +$	$x_2 -$	$x_2 -$	$x_2 -$
x_3	■	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 +$	$x_3 -$
x_4	■	$x_4 -$	$x_4 -$	$x_4 +$	$x_4 +$	$x_4 +$
x_5	■	$x_5 +$	$x_5 -$	$x_5 +$	$x_5 -$	$x_5 +$
		↓	↓	↓	↓	↓
		h_1	h_2	h_3	h_4	h_5

Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC	LN	L	need diversity when designing code
Tree			

training time: how many training points are created

prediction time: how many binary predictions are made

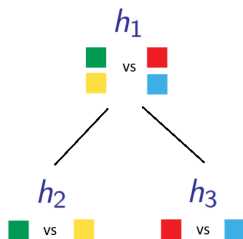


Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC	LN	L	need diversity when designing code
Tree	$\mathcal{O}((\log_2 C)N)$		

training time: how many training points are created

prediction time: how many binary predictions are made

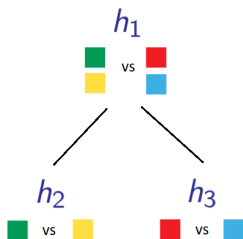


Comparisons

Reduction	training time	prediction time	remark
OvA	CN	C	not robust
OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC	LN	L	need diversity when designing code
Tree	$\mathcal{O}((\log_2 C)N)$	$\mathcal{O}(\log_2 C)$	

training time: how many training points are created

prediction time: how many binary predictions are made

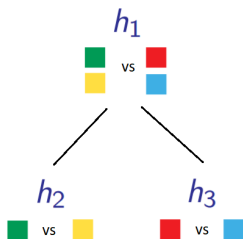


Comparisons

Reduction	training time	prediction time	remark
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OvO	$(C - 1)N$	$\mathcal{O}(C^2)$	can achieve very small training error
ECOC	LN	L	need diversity when designing code
Tree	$\mathcal{O}((\log_2 C)N)$	$\mathcal{O}(\log_2 C)$	good for "extreme classification"

training time: how many training points are created

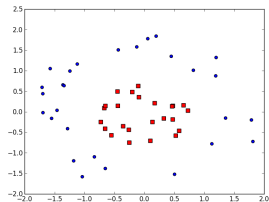
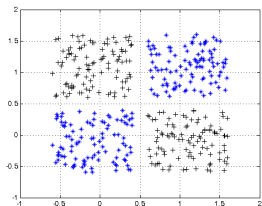
prediction time: how many binary predictions are made



Outline

- 1 Review of Last Lecture
- 2 Multiclass Classification
- 3 Neural Nets
 - Definition
 - Backpropagation
 - Preventing overfitting

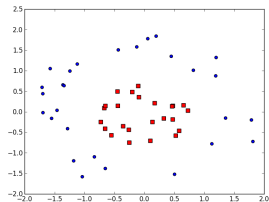
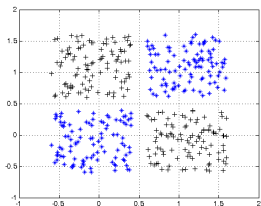
Linear models are not always adequate



We can use a nonlinear mapping as discussed:

$$\phi(x) : x \in \mathbb{R}^D \rightarrow z \in \mathbb{R}^M$$

Linear models are not always adequate

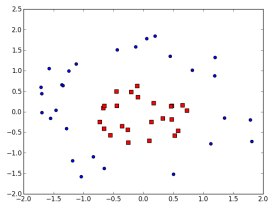
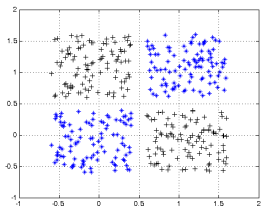


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Linear models are not always adequate



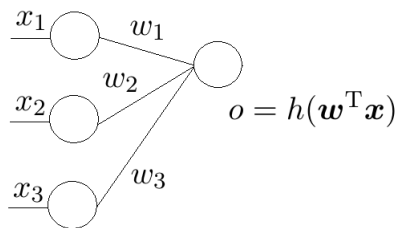
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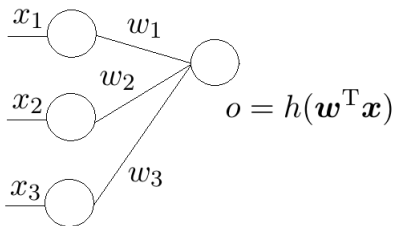
The most popular nonlinear models nowadays: **neural nets**

Linear model as a one-layer neural net



$h(a) = a$ for linear model

Linear model as a one-layer neural net

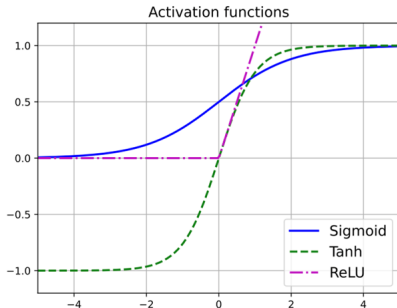


$$h(a) = a \text{ for linear model}$$

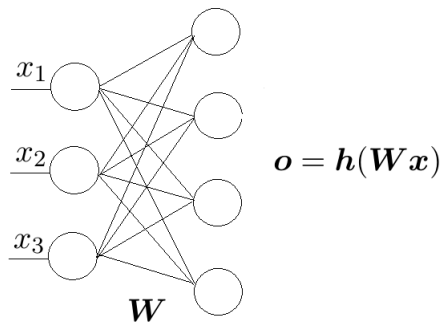
To create non-linearity, can use

- Rectified Linear Unit (**ReLU**):

$$h(a) = \max\{0, a\}$$
- sigmoid function:
$$h(a) = \frac{1}{1+e^{-a}}$$
- TanH:
$$h(a) = \frac{e^a - e^{-a}}{e^a + e^{-a}}$$
- many more

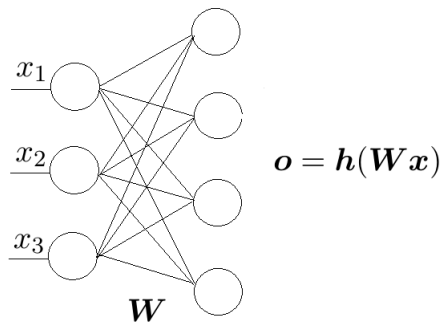


More output nodes



$\mathbf{W} \in \mathbb{R}^{4 \times 3}$, $\mathbf{h} : \mathbb{R}^4 \rightarrow \mathbb{R}^4$ so $\mathbf{h}(\mathbf{a}) = (h_1(a_1), h_2(a_2), h_3(a_3), h_4(a_4))$

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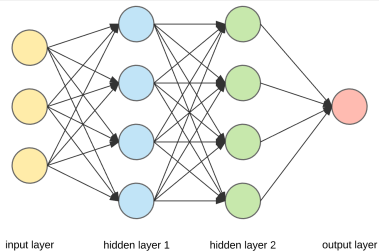


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Can think of this as a nonlinear mapping: $\phi(\mathbf{x}) = \mathbf{h}(\mathbf{W}\mathbf{x})$

More layers

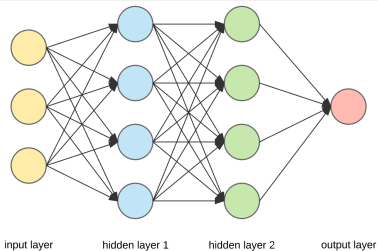
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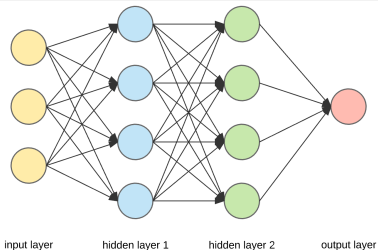
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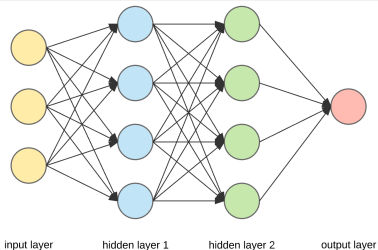
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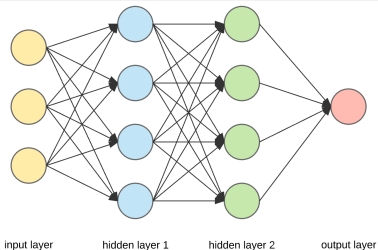
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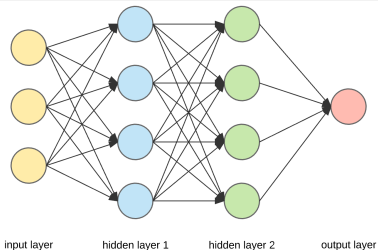
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- #layers refers to #hidden_layers (plus 1 or 2 for input/output layers)
- **deep** neural nets can have many layers and *millions* of parameters
- this is a **feedforward, fully connected** neural net, there are many variants (convolutional nets, recurrent nets, transformers, etc.)



How powerful are neural nets?

Universal approximation theorem (Cybenko, 89; Hornik, 91):

A feedforward neural net with a single hidden layer can approximate any continuous functions.

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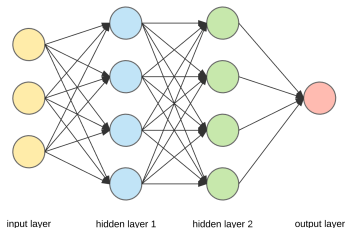
Designing network architecture is important and very complicated

- for feedforward network, need to decide number of hidden layers, number of neurons at each layer, activation functions, etc.

Math formulation

An L-layer neural net can be written as

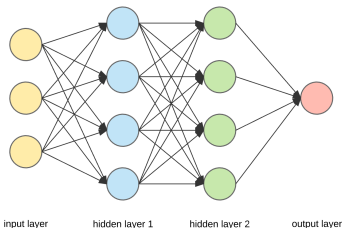
$$f(\mathbf{x}) = \mathbf{h}_L(\mathbf{W}_L \mathbf{h}_{L-1}(\mathbf{W}_{L-1} \cdots \mathbf{h}_1(\mathbf{W}_1 \mathbf{x})))$$



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To ease notation, for a given input \mathbf{x} , define recursively

$$\mathbf{o}_0 = \mathbf{x}, \quad \mathbf{a}_\ell = \mathbf{W}_\ell \mathbf{o}_{\ell-1}, \quad \mathbf{o}_\ell = \mathbf{h}_\ell(\mathbf{a}_\ell) \quad (\ell = 1, \dots, L)$$

where

- $\mathbf{W}_\ell \in \mathbb{R}^{D_\ell \times D_{\ell-1}}$ is the weights between layer $\ell - 1$ and ℓ
- $D_0 = D, D_1, \dots, D_L$ are numbers of neurons at each layer
- $\mathbf{a}_\ell \in \mathbb{R}^{D_\ell}$ is input to layer ℓ
- $\mathbf{o}_\ell \in \mathbb{R}^{D_\ell}$ is output of layer ℓ
- $\mathbf{h}_\ell : \mathbb{R}^{D_\ell} \rightarrow \mathbb{R}^{D_\ell}$ is activation functions at layer ℓ

Learning the model

No matter how complicated the model is, our goal is the same: minimize

$$F(\mathbf{W}_1, \dots, \mathbf{W}_L) = \frac{1}{N} \sum_{n=1}^N F_n(\mathbf{W}_1, \dots, \mathbf{W}_L)$$

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where

$$F_n(\mathbf{W}_1, \dots, \mathbf{W}_L) = \begin{cases} \|\mathbf{f}(\mathbf{x}_n) - \mathbf{y}_n\|_2^2 & \text{for regression} \\ \ln \left(1 + \sum_{k \neq y_n} e^{f(\mathbf{x}_n)_k - f(\mathbf{x}_n)_{y_n}} \right) & \text{for classification} \end{cases}$$

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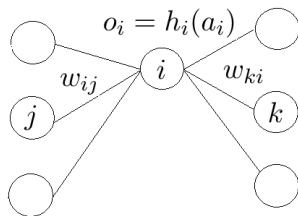
$$\frac{\partial f}{\partial w} = \sum_{i=1}^d \frac{\partial f}{\partial g_i} \frac{\partial g_i}{\partial w}$$

the simplest example $f(g_1(w), g_2(w)) = g_1(w)g_2(w)$

Computing the derivative

Drop the subscript ℓ for layer for simplicity.

Find the **derivative of F_n w.r.t. to w_{ij}**

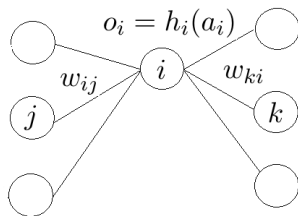


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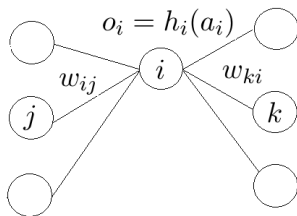
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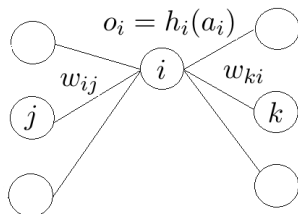


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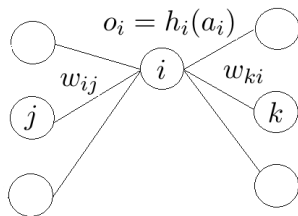


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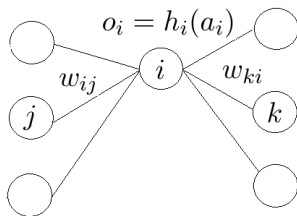
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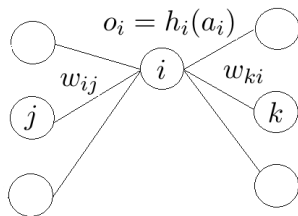
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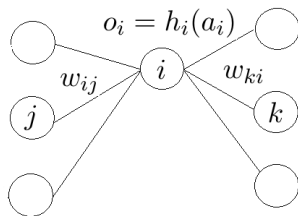
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Computing the derivative

Adding the subscript for layer:

$$\frac{\partial F_n}{\partial w_{\ell,ij}} = \frac{\partial F_n}{\partial a_{\ell,i}} o_{\ell-1,j}$$

$$\frac{\partial F_n}{\partial a_{\ell,i}} = \left(\sum_k \frac{\partial F_n}{\partial a_{\ell+1,k}} w_{\ell+1,ki} \right) h'_{\ell,i}(a_{\ell,i})$$

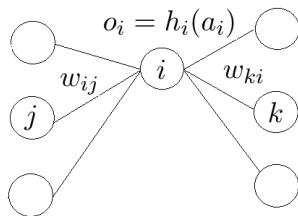


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For the last layer, for square loss

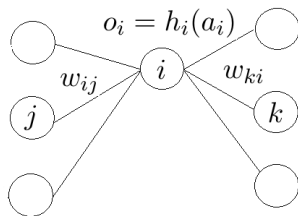
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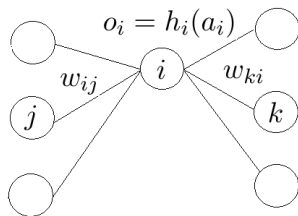
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Exercise: try to do it for cross-entropy loss yourself.

Computing the derivative

Using **matrix notation** greatly simplifies presentation and implementation:

$$\frac{\partial F_n}{\partial \mathbf{W}_\ell} = \frac{\partial F_n}{\partial \mathbf{a}_\ell} \mathbf{o}_{\ell-1}^T \in \mathbb{R}^{D_\ell \times D_{\ell-1}}$$

$$\frac{\partial F_n}{\partial \mathbf{a}_\ell} = \begin{cases} \left(\mathbf{W}_{\ell+1}^T \frac{\partial F_n}{\partial \mathbf{a}_{\ell+1}} \right) \circ \mathbf{h}'_\ell(\mathbf{a}_\ell) & \text{if } \ell < L \\ 2(\mathbf{h}_L(\mathbf{a}_L) - \mathbf{y}_n) \circ \mathbf{h}'_L(\mathbf{a}_L) & \text{else} \end{cases}$$

where $\mathbf{v}_1 \circ \mathbf{v}_2 = (v_{11}v_{21}, \dots, v_{1D}v_{2D})$ is the element-wise product (a.k.a. Hadamard product).

Verify yourself!

Putting everything into SGD

The **backpropagation** algorithm (**Backprop**)

Initialize $\mathbf{W}_1, \dots, \mathbf{W}_L$ randomly.

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$$\frac{\partial F_n}{\partial \mathbf{a}_\ell} = \begin{cases} \left(\mathbf{W}_{\ell+1}^\top \frac{\partial F_n}{\partial \mathbf{a}_{\ell+1}} \right) \circ \mathbf{h}'_\ell(\mathbf{a}_\ell) & \text{if } \ell < L \\ 2(\mathbf{h}_L(\mathbf{a}_L) - \mathbf{y}_n) \circ \mathbf{h}'_L(\mathbf{a}_L) & \text{else} \end{cases}$$

- update weights

$$\mathbf{W}_\ell \leftarrow \mathbf{W}_\ell - \eta \frac{\partial F_n}{\partial \mathbf{W}_\ell} = \mathbf{W}_\ell - \eta \frac{\partial F_n}{\partial \mathbf{a}_\ell} \mathbf{o}_{\ell-1}^\top$$

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(Important: *should \mathbf{W}_ℓ be overwritten immediately in the last step?*)

Important tricks to optimize neural nets

Many important tricks on top on Backprop

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- **momentum**: make use of previous gradients (taking inspiration from physics)
- ...

SGD with momentum (a simple version)

Initialize w_0 and **velocity** $v = \mathbf{0}$

For $t = 1, 2, \dots$

- form a stochastic gradient g_t
- update velocity $v \leftarrow \alpha v + g_t$ for some discount factor $\alpha \in (0, 1)$
- update weight $w_t \leftarrow w_{t-1} - \eta v$

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Updates for first few rounds:

- $w_1 = w_0 - \eta g_1$
- $w_2 = w_1 - \alpha \eta g_1 - \eta g_2$
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Adam (most popular) \approx SGD + adaptive learning rate + momentum

Overfitting

Overfitting is very likely since neural nets are too powerful.

Methods to overcome overfitting:

- data augmentation
- regularization
- dropout
- early stopping
- ...

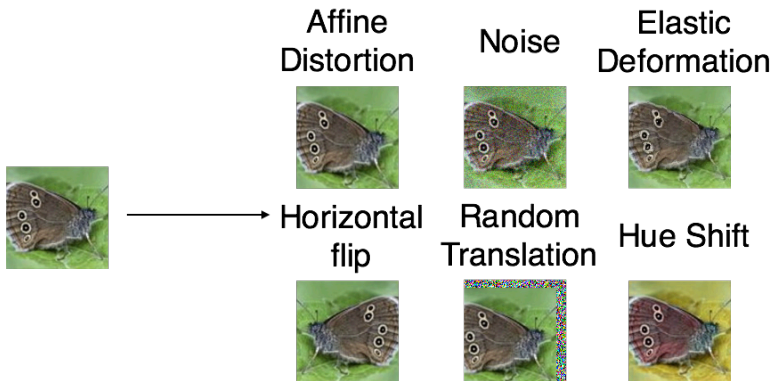
Data augmentation

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Exploit prior knowledge to add more training data



Regularization

L2 regularization: minimize

$$F'(\mathbf{W}_1, \dots, \mathbf{W}_L) = F(\mathbf{W}_1, \dots, \mathbf{W}_L) + \lambda \sum_{\ell=1}^L \|\mathbf{W}_\ell\|_2^2$$

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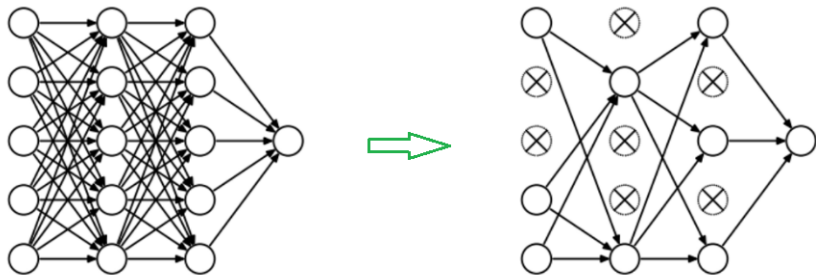
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Introduce *weight decaying effect*

Dropout

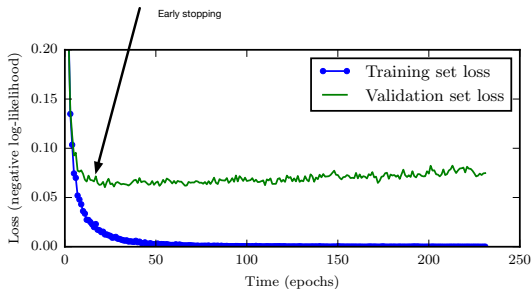
Independently delete each neuron with a fixed probability (say 0.5), during each iteration of Backprop (only for training, not for testing)



Very effective, makes training faster as well

Early stopping

Stop training when the performance on validation set stops improving



Conclusions for neural nets

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- do need *a lot of data* to work well
- take *a lot of time* to train (need GPUs for massive parallel computing)
- take some work to select architecture and hyperparameters
- are still not well understood in theory