## CSCI567 Machine Learning (Spring 2025)

Haipeng Luo

University of Southern California

Feb 28, 2025



Date: Friday, March 7th

Time: 1:00-3:20pm

**Location**: THH 101 (double seating), waiting for an overflow room (will announce on Piazza)

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Individual effort, close-book (no cheat sheet), no calculators or any other electronics, *but need your phone to upload your solutions to Gradescope from 3:20-3:30pm* 

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Tips: expect to see variants of questions from discussion/homework

Formulas provided:

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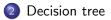
Most other formulas are not needed (*do not overthink!*)

• Taylor expansion, complete Backprop algorithm in matrix form, KKT conditions, etc.





1 Review of last lecture





#### Outline



#### 1 Review of last lecture



### Support Vector Machine

#### SVM: max-margin linear classifier

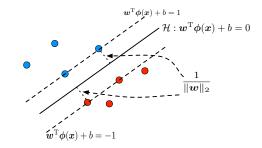
**Primal** (equivalent to minimizing L2 regularized hinge loss):

$$\begin{split} \min_{\boldsymbol{w}, b, \{\xi_n\}} & C\sum_n \xi_n + \frac{1}{2} \|\boldsymbol{w}\|_2^2 \\ \text{s.t.} & 1 - y_n(\boldsymbol{w}^{\mathrm{T}} \boldsymbol{\phi}(\boldsymbol{x}_n) + b) \leq \xi_n, \quad \forall \ n \\ & \xi_n \geq 0, \quad \forall \ n \end{split}$$

Dual (kernelizable, reveals what training points are support vectors):

$$\max_{\{\alpha_n\}} \quad \sum_n \alpha_n - \frac{1}{2} \sum_{m,n} y_m y_n \alpha_m \alpha_n \boldsymbol{\phi}(\boldsymbol{x}_m)^{\mathrm{T}} \boldsymbol{\phi}(\boldsymbol{x}_n)$$
s.t. 
$$\sum_n \alpha_n y_n = 0 \quad \text{and} \quad 0 \le \alpha_n \le C, \quad \forall \ n$$

#### Separable Case



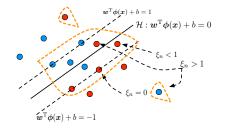
#### Geometric interpretation of support vectors

A support vector satisfies  $\alpha_n^* \neq 0$  and

$$1 - \xi_n^* - y_n(\boldsymbol{w}^{*\mathrm{T}}\boldsymbol{\phi}(\boldsymbol{x}_n) + b^*) = 0$$

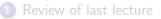
When

- $\xi_n^* = 0$ ,  $y_n(\boldsymbol{w}^{*\mathrm{T}}\boldsymbol{\phi}(\boldsymbol{x}_n) + b^*) = 1$ and thus the point is  $1/\|\boldsymbol{w}^*\|_2$ away from the hyperplane.
- ξ<sub>n</sub><sup>\*</sup> < 1, the point is classified correctly but does not satisfy the large margin constraint.
- $\xi_n^* > 1$ , the point is misclassified.



Support vectors (circled with the orange line) are *the only points that matter*!

#### Outline



#### 2 Decision tree

- The model
- Learning a decision tree



We have seen different ML models for classification/regression:

• linear models, neural nets and other nonlinear models induced by kernels

#### The model

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- **Decision tree** is yet another one:
  - nonlinear in general

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- works for both classification and regression; we focus on classification
- one key advantage is good interpretability
- not to be confused with the "tree reduction" in Lec 4
- still very popular for small tabular data, especially when used in ensemble (i.e. "forest")

#### Tree-based models outperform neural nets sometimes

# Why do tree-based models still outperform deep learning on tabular data?

Léo Grinsztajn Soda, Inria Saclay leo.grinsztajn@inria.fr Edouard Oyallon ISIR, CNRS, Sorbonne University Gaël Varoquaux Soda, Inria Saclay

#### Abstract

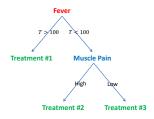
While deep learning has enabled tremendous progress on text and image datasets. its superiority on tabular data is not clear. We contribute extensive benchmarks of standard and novel deep learning methods as well as tree-based models such as XGBoost and Random Forests, across a large number of datasets and hyperparameter combinations. We define a standard set of 45 datasets from varied domains with clear characteristics of tabular data and a benchmarking methodology accounting for both fitting models and finding good hyperparameters. Results show that treebased models remain state-of-the-art on medium-sized data (~10K samples) even without accounting for their superior speed. To understand this gap, we conduct an empirical investigation into the differing inductive biases of tree-based models and Neural Networks (NNs). This leads to a series of challenges which should guide researchers aiming to build tabular-specific NNs: 1. be robust to uninformative features, 2. preserve the orientation of the data, and 3. be able to easily learn irregular functions. To stimulate research on tabular architectures, we contribute a standard benchmark and raw data for baselines: every point of a 20 000 compute hours hyperparameter search for each learner.

#### The model

#### Example

Many decisions are made based on some tree structure

#### **Medical treatment**



#### The model

#### Example

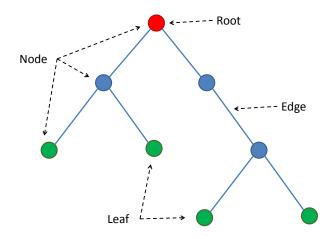
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**Medical treatment** 

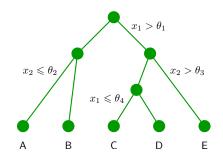
#### Salary in a company



### Tree terminology

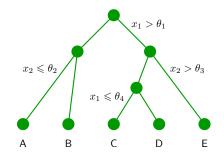


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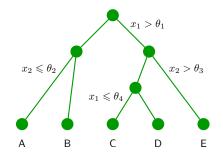
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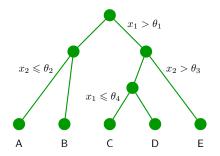
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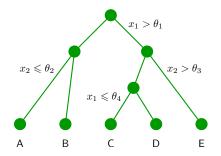


# A more abstract example of decision trees

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- finally the leaf gives the prediction  $f(\boldsymbol{x})$



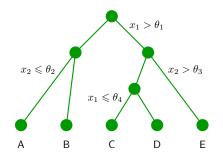
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For example,  $f((\theta_1 - 1, \theta_2 + 1)) = B$ 

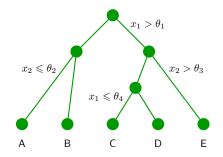


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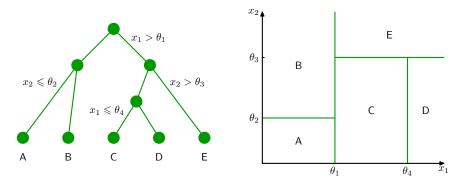


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Complex to formally write down, but easy to represent pictorially or as codes.

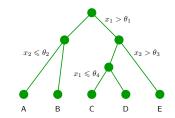
# The decision boundary

Corresponds to a classifier with boundaries:



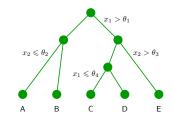
#### The model

#### **Parameters**

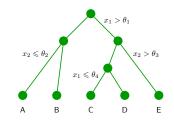


Parameters to learn for a decision tree:

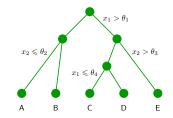
 $\bullet$  the structure of the tree, such as the depth,  $\# branches, \ \# nodes, \ etc$ 



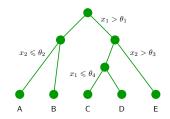
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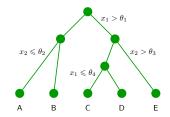
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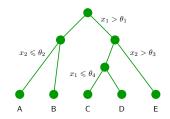
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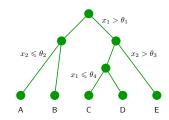
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• the value/prediction of the leaves (A, B, ...)



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Instead, we turn to some greedy top-down approach.

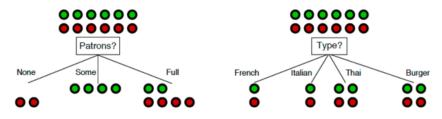
# A running example

[Russell & Norvig, AIMA]

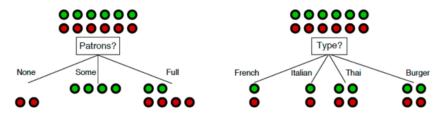
- predict whether a customer will wait for a table at a restaurant
- 12 training examples
- 10 features (all discrete)

Example	Attributes										Target
	Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	WillWait
$X_1$	T	F	F	Т	Some	\$\$\$	F	Т	French	0–10	Т
$X_2$	T	F	F	Т	Full	\$	F	F	Thai	30–60	F
$X_3$	F	T	F	F	Some	\$	F	F	Burger	0–10	T
$X_4$	T	F	Τ	Т	Full	\$	F	F	Thai	10–30	T
$X_5$	T	F	Τ	F	Full	\$\$\$	F	T	French	>60	F
$X_6$	F	T	F	Т	Some	\$\$	Т	T	Italian	0–10	T
$X_7$	F	T	F	F	None	\$	T	F	Burger	0–10	F
$X_8$	F	F	F	Т	Some	\$\$	T	T	Thai	0–10	T
$X_9$	F	T	Τ	F	Full	\$	Т	F	Burger	>60	F
$X_{10}$	T	T	Τ	Т	Full	\$\$\$	F	T	Italian	10–30	F
$X_{11}$	F	F	F	F	None	\$	F	F	Thai	0–10	F
$X_{12}$	T	Т	Т	Т	Full	\$	F	F	Burger	<i>30–60</i>	Т

I.e., which feature should we test at the root? Examples:

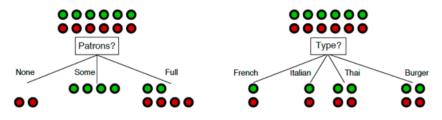


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Which split is better?

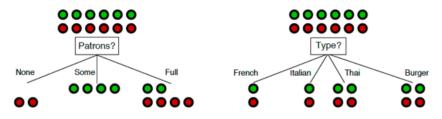
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Which split is better?

- intuitively "patrons" is a better feature since it leads to "more pure" or "more certain" children
- how to quantify this intuition?

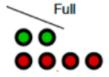
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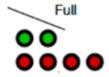
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One classic uncertainty measure of a distribution is its (Shannon) entropy:

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#### Learning a decision tree

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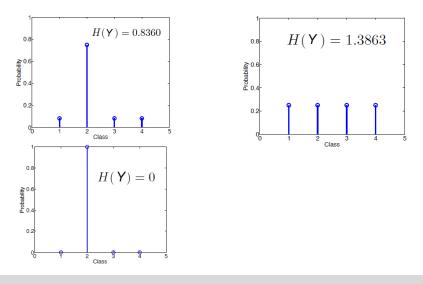
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  - e.g.  $P = (1, 0, \dots, 0)$
  - $0 \log 0$  is defined naturally as  $\lim_{z \to 0+} z \log z = 0$

# Examples of computing entropy

With base e and 4 classes:



# Another example

Entropy in each child if root tests on "patrons"

For "None" branch

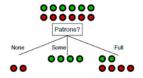
$$-\left(\frac{0}{0+2}\log\frac{0}{0+2} + \frac{2}{0+2}\log\frac{2}{0+2}\right) = 0$$

For "Some" branch

$$-\left(\frac{4}{4+0}\log\frac{4}{4+0} + \frac{0}{4+0}\log\frac{0}{4+0}\right) = 0$$

For "Full" branch

$$-\left(\frac{2}{2+4}\log\frac{2}{2+4} + \frac{4}{2+4}\log\frac{4}{2+4}\right) \approx 0.9$$



# Another example

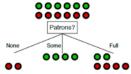
Entropy in each child if root tests on "patrons"

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For "None" branch  $-\left(\frac{0}{0+2}\log\frac{0}{0+2} + \frac{2}{0+2}\log\frac{2}{0+2}\right) = 0$ For "Some" branch  $-\left(\frac{4}{4+0}\log\frac{4}{4+0} + \frac{0}{4+0}\log\frac{0}{4+0}\right) = 0$ For "Full" branch  $-\left(\frac{2}{2+4}\log\frac{2}{2+4} + \frac{4}{2+4}\log\frac{4}{2+4}\right) \approx 0.9$ 

So how good is choosing "patrons" overall? Very naturally, we take the weighted average of entropy:

$$\frac{2}{12} \times 0 + \frac{4}{12} \times 0 + \frac{6}{12} \times 0.9 = 0.45$$

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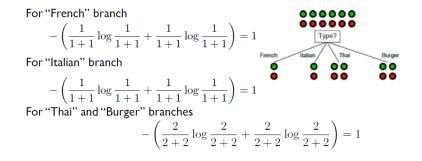
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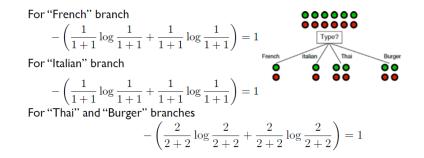
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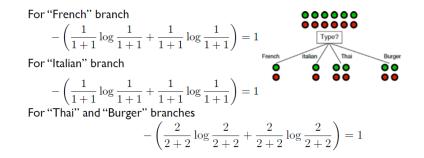
Pick the feature that leads to the smallest conditional entropy.

*a*"

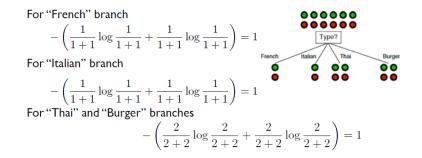




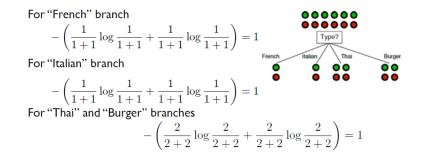
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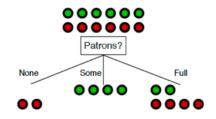


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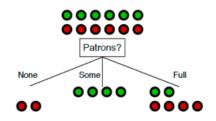
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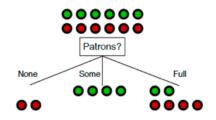
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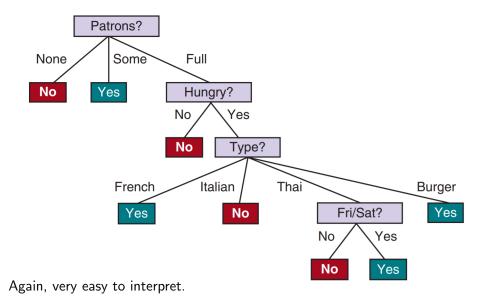
### Repeat recursively

#### Split each child in the same way.

- but no need to split children "none" and "some": they are pure already and become leaves
- for "full", repeat, focusing on those 6 examples:



		Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	WillWait
ľ	$X_1$	Т	F	F	Т	Some	\$\$\$	F	Т	French	0–10	Т
	$X_2$	Т	F	F	Т	Full	\$	F	F	Thai	30–60	F
	$X_3$	F	Т	F	F	Some	\$	F	F	Burger	0–10	Т
	$X_4$	Т	F	Т	Т	Full	\$	F	F	Thai	10–30	Т
	$X_5$	Т	F	Т	F	Full	\$\$\$	F	Т	French	>60	F
	$X_6$	F	Т	F	Т	Some	\$\$	Т	Т	Italian	0–10	Т
	$X_7$	F	T	F	F	None	\$	Т	F	Burger	0–10	F
	$X_8$	F	F	F	Т	Some	\$\$	Т	Т	Thai	0–10	Т
	$X_9$	F	Т	Т	F	Full	\$	Т	F	Burger	>60	F
	$X_{10}$	Т	Т	Т	Т	Full	\$\$\$	F	Т	Italian	10–30	F
	$X_{11}$	F	F	F	F	None	\$	F	F	Thai	0–10	F
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- else if Examples is empty, return a leaf with majority class of parent

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• if a feature is continuous, we need to find a threshold that leads to minimum conditional entropy or Gini impurity. *Think about how to do it efficiently.* 

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- restrict the depth or #nodes
- other more principled approaches
- all make use of a validation set

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- much better performance than a single tree, trivially parallelizable!

### Outline

Review of last lecture

### Decision tree

### 3 Boosting

- Examples
- AdaBoost
- Derivation of AdaBoost

## Introduction

**Boosting** (an even more powerful/general ensemble method):

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We again focus on binary classification.

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  - even if it's not obvious how to deal with weight directly, we can always resample according to *D* to create a new unweighted dataset

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Focus on AdaBoost, one of the most successful boosting algorithms.

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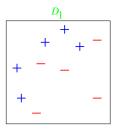
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Output the final classifier  $H(\boldsymbol{x}) = \operatorname{sgn}\left(\sum_{t=1}^{T} \beta_t h_t(\boldsymbol{x})\right)$ 

### Example

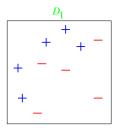
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The size of + or - indicates the weight, which starts from uniform  $D_1$ 

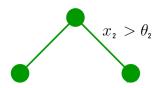


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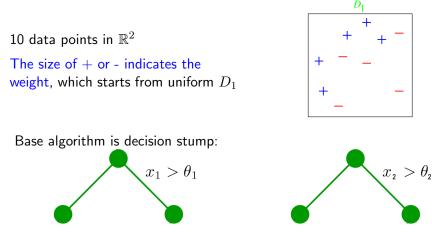
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Base algorithm is decision stump:  $x_1 > \theta_1$ 

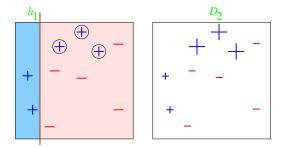


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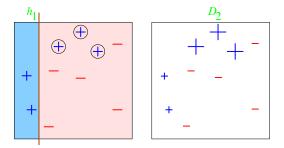
Observe that no stump can predict very accurately for this dataset

### Round 1: t = 1



• 3 misclassified (circled):  $\epsilon_1 = 0.3 \rightarrow \beta_1 = \frac{1}{2} \ln \left( \frac{1-\epsilon_t}{\epsilon_t} \right) \approx 0.42.$ 

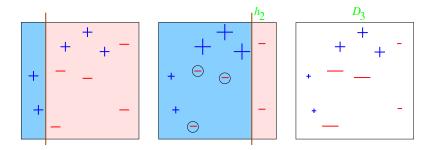
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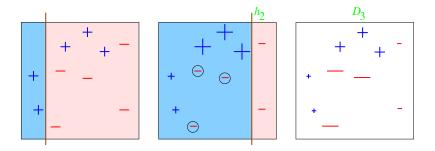
•  $D_2$  puts more weights on those examples

### Round 2: t = 2



• 3 misclassified (circled):  $\epsilon_2 = 0.21 \rightarrow \beta_2 = 0.65$ .

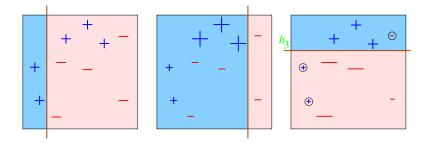
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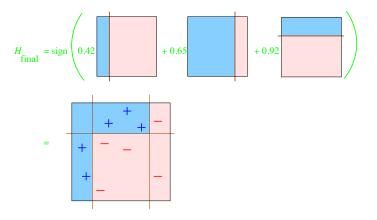
•  $D_3$  puts more weights on those examples

### Round 3: t = 3

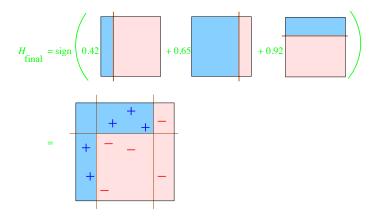


• again 3 misclassified (circled):  $\epsilon_3 = 0.14 \rightarrow \beta_3 = 0.92$ .

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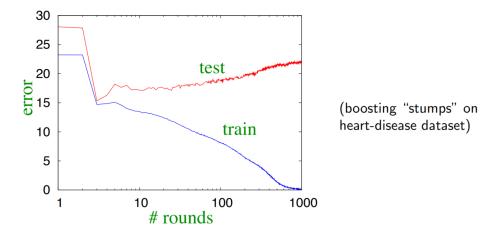
All data points are now classified correctly, even though each weak classifier makes 3 mistakes.

# Overfitting

When T is large, the model is very complicated and overfitting can happen

# Overfitting

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#### AdaBoost

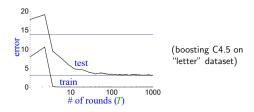
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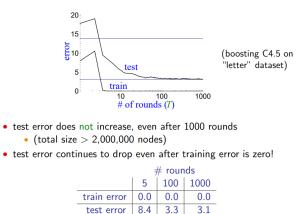
- test error does not increase, even after 1000 rounds
  - (total size > 2,000,000 nodes)
- test error continues to drop even after training error is zero!

	# rounds		
	5	100	1000
train error	0.0	0.0	0.0
test error	8.4	3.3	3.1

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Used to be a mystery, but by now rigorous theory has been developed to explain this phenomenon.

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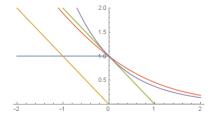
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Step 2: the loss that AdaBoost minimizes is the exponential loss

$$\sum_{n=1}^{\mathsf{N}} \exp\left(-y_n f(\boldsymbol{x}_n)\right)$$



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where the last step is by the definition of weights

$$D_t(n) \propto D_{t-1}(n) \exp\left(-y_n \beta_{t-1} h_{t-1}(\boldsymbol{x}_n)\right) \propto \cdots \propto \exp\left(-y_n f_{t-1}(\boldsymbol{x}_n)\right)$$

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This greedy step is abstracted out through a base algorithm.

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Keep doing this greedy minimization gives the AdaBoost algorithm.

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AdaBoost is often resistant to overfitting.